Identifying vertices of a graph using paths

<u>Florent Foucaud</u> (PhD student at LaBRI, Bordeaux, France) and Matjaž Kovše (Postdoc at Universität Leipzig, Germany)

> Kalasalingam University Tamil Nadu, India

> > 19-21 July 2012

IWOCA 2012

The test cover problem (TCP)

Definition - Test cover problem (mentioned in Garey, Johnson, 1979)

INPUT: a set system (or hypergraph) (X, S)PROBLEM: find the minimum subset $T \subseteq S$ such that each element $x \in X$ belongs to a different set of sets in T.

The test cover problem (TCP)

Definition - Test cover problem (mentioned in Garey, Johnson, 1979)

INPUT: a set system (or hypergraph) (X, S)PROBLEM: find the minimum subset $T \subseteq S$ such that each element $x \in X$ belongs to a different set of sets in T.

Remark

Equivalently: for any pair x, y of elements of X, there is a set in T that contains **exactly** one of x, y.

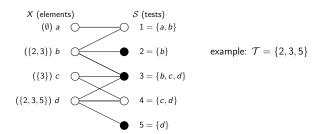
The test cover problem (TCP)

Definition - Test cover problem (mentioned in Garey, Johnson, 1979)

INPUT: a set system (or hypergraph) (X, S)PROBLEM: find the minimum subset $T \subseteq S$ such that each element $x \in X$ belongs to a different set of sets in T.

Remark

Equivalently: for any pair x, y of elements of X, there is a set in T that contains **exactly** one of x, y.

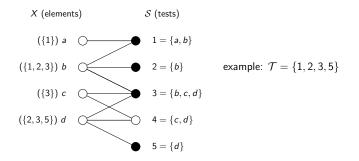


Definition - Identification problem

INPUT: a set system (or hypergraph) (X, S)PROBLEM: find the minimum subset $T \subseteq S$ such that each element $x \in X$ belongs to a different **nonempty** set of sets in T.

Definition - Identification problem

INPUT: a set system (or hypergraph) (X, S)PROBLEM: find the minimum subset $T \subseteq S$ such that each element $x \in X$ belongs to a different **nonempty** set of sets in T.



- Fault analysis: tests are fault-detectors
- medical diagnostics: tests are tests for diseases
- biological identification: tests are attributes

Theorem (Folklore)

Given a set system (X, S), a solution to the TCP has size at least $\log_2(|X|)$. A solution to the IDP has size at least $\log_2(|X|+1)$. These bounds are tight.

Proof: Must assign to each element of X, a distinct subset of \mathcal{T} . Hence $|X| \leq 2^{|\mathcal{T}|}$ (TCP) and $|X| \leq 2^{|\mathcal{T}|} - 1$ (IDP). Theorem (Folklore)

Given a set system (X, S), a solution to the TCP has size at least $\log_2(|X|)$. A solution to the IDP has size at least $\log_2(|X|+1)$. These bounds are tight.

Proof: Must assign to each element of X, a distinct subset of \mathcal{T} . Hence $|X| \leq 2^{|\mathcal{T}|}$ (TCP) and $|X| \leq 2^{|\mathcal{T}|} - 1$ (IDP).

Theorem (Bondy's theorem, 1972)

Given a set system (X, S), a minimal solution to the TCP has size at most |X| - 1. A minimal solution to the IDP has size at most |X|. These bounds are tight.

Proof: TCP: nice graph-theoretic argument. IDP: sizes of solutions to TCP and IDP differ by at most 1!

Florent Foucaud

Identifying vertices of a graph using paths

Definition - *k*-bounded Test Cover Problem and Identification Problem

INPUT: a set system (X, S) such that each test has size at most kPROBLEM: find the minimum subset $T \subseteq S$ such that each element $x \in X$ belongs to a different (nonempty) set of sets in T. **Definition** - k-bounded Test Cover Problem and Identification Problem

INPUT: a set system (X, S) such that each test has size at most kPROBLEM: find the minimum subset $T \subseteq S$ such that each element $x \in X$ belongs to a different (nonempty) set of sets in T.

Theorem (Moret and Shapiro, 1985)

Given a k-bounded set system (X, S), a solution to the TCP or IDP has size at least $\frac{2|X|}{k+1}$. This bound is tight.

Proof: i_1 : elements belonging to 1 test of \mathcal{T} ; i_2 : elements in at least 2 tests

$$\begin{aligned} &i_1 \le |\mathcal{T}|, \ i_2 \le \frac{|\mathcal{T}|k-i_1|}{2} \\ &|X| = i_1 + i_2 \le |\mathcal{T}| + \frac{|\mathcal{T}|k-i_1|}{2} = \frac{|\mathcal{T}|(k+1)|}{2} \end{aligned}$$

Florent Foucaud

Complexity results

Theorem (Garey, Johnson, 1979)

TCP is NP-complete.

Theorem (Charon, Cohen, Hudry, Lobstein, 2008)

IDP is NP-complete (even in "planar" set systems).

Complexity results

Theorem (Garey, Johnson, 1979)

TCP is NP-complete.

Theorem (Charon, Cohen, Hudry, Lobstein, 2008)

IDP is NP-complete (even in "planar" set systems).

Theorem (De Bontridder, Haldorsson, Haldorsson, Hurkens, Lenstra, Ravi, Stougie, 2003)

TCP is $O(\log(|X|))$ -approximable, but NP-hard to approximate within o(log(|X|)). TCP-k is $O(\log(k))$ -approximable.

Proof: Reductions from and to SET-COVER and *k*-BOUNDED SET COVER.

Complexity results

Theorem (Garey, Johnson, 1979)

TCP is NP-complete.

Theorem (Charon, Cohen, Hudry, Lobstein, 2008)

IDP is NP-complete (even in "planar" set systems).

Theorem (De Bontridder, Haldorsson, Haldorsson, Hurkens, Lenstra, Ravi, Stougie, 2003)

TCP is $O(\log(|X|))$ -approximable, but NP-hard to approximate within o(log(|X|)). TCP-k is $O(\log(k))$ -approximable.

Proof: Reductions from and to SET-COVER and *k*-BOUNDED SET COVER.

Remark: The same holds for IDP and IDP-*k*.

Florent Foucaud

Special cases of IDP

Rich literature (250+ publications) on variants arising from **graph theory**:

Definition - Identifying codes (Karpovsky, Chakrabarty, Levitin, 1998)

Given a graph G, it is the IDP problem where X = V(G) and S is the set of **closed neighbourhoods** in G (a vertex identifies its neighbours and itself).

Special cases of IDP

Rich literature (250+ publications) on variants arising from **graph theory**:

Definition - Identifying codes (Karpovsky, Chakrabarty, Levitin, 1998)

Given a graph G, it is the IDP problem where X = V(G) and S is the set of **closed neighbourhoods** in G (a vertex identifies its neighbours and itself).

Definition - Watching systems (Auger, Charon, Hudry, Lobstein, 2010+)

Given a graph G, it is the IDP problem where X = V(G) and S is the set of **stars** in G (a vertex identifies a part of its neighbourhood).

Special cases of IDP

Rich literature (250+ publications) on variants arising from **graph theory**:

Definition - Identifying codes (Karpovsky, Chakrabarty, Levitin, 1998)

Given a graph G, it is the IDP problem where X = V(G) and S is the set of **closed neighbourhoods** in G (a vertex identifies its neighbours and itself).

Definition - Watching systems (Auger, Charon, Hudry, Lobstein, 2010+)

Given a graph G, it is the IDP problem where X = V(G) and S is the set of **stars** in G (a vertex identifies a part of its neighbourhood).

Motivation: fault-detection in computer networks or location of threats in facilities

Florent Foucaud

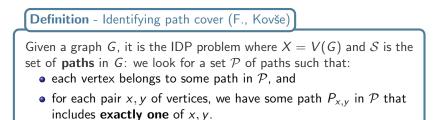
The path identifying cover problem



Given a graph G, it is the IDP problem where X = V(G) and S is the set of **paths** in G: we look for a set \mathcal{P} of paths such that:

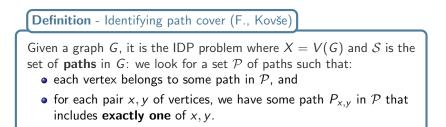
- \bullet each vertex belongs to some path in $\mathcal P,$ and
- for each pair x, y of vertices, we have some path $P_{x,y}$ in \mathcal{P} that includes **exactly one** of x, y.

The path identifying cover problem



Possible motivations: laser-like sensor systems or patrolling robots in facilities/networks

The path identifying cover problem



Possible motivations: laser-like sensor systems or patrolling robots in facilities/networks

Notation - $p^{\text{ID}}(G)$

minimum number of paths needed in an identifying path cover.

To distinguish two adjacent vertices: need a path stopping at one of them.

 P_n, C_n : the path and cycle on n vertices.

Theorem (F., Kovše) We have: • $p^{\text{ID}}(P_n) = \lceil \frac{n+1}{2} \rceil$ • $p^{\text{ID}}(C_3) = 2, p^{\text{ID}}(C_4) = 3$ • for $n \ge 5, p^{\text{ID}}(C_n) = \lceil \frac{n}{2} \rceil$ The optimum is roughly to cover three leaves using two paths.

 $K_{1,n-1}$: star on *n* vertices.

Theorem (F., Kovše)

We have
$$p^{\mathbb{D}}(K_{1,n-1}) = \lceil \frac{2(n-1)}{3} \rceil$$
.



Same idea can be used for trees.

T: tree with ℓ leaves, *t* degree 2 vertices.

Identify all vertices that are not of degree 2 using $\lceil \frac{2(\ell-1)}{3} \rceil$ paths. Intuition: first contract the tree to a star, then de-contract it level by level; at each step, re-route paths accordingly.

Degree 2 vertices can be identified using at most $\lceil \frac{t}{2} \rceil$ additional paths.

 Theorem (F., Kovše)

 $p^{\text{ID}}(T) \leq \lceil \frac{2\ell}{3} \rceil + \lceil \frac{t}{2} \rceil$



Same idea can be used for trees.

T: tree with ℓ leaves, *t* degree 2 vertices.

Identify all vertices that are not of degree 2 using $\lceil \frac{2(\ell-1)}{3} \rceil$ paths. Intuition: first contract the tree to a star, then de-contract it level by level; at each step, re-route paths accordingly.

Degree 2 vertices can be identified using at most $\lceil \frac{t}{2} \rceil$ additional paths.

Theorem (F., Kovše)

$$p^{\text{ID}}(T) \leq \left\lceil \frac{2\ell}{3} \right\rceil + \left\lceil \frac{t}{2} \right\rceil$$

Corollary

Let G be a **connected** graph. Then $p^{\mathbb{D}}(G) \leq \lceil \frac{2n}{3} \rceil$.

Proof: Take spanning tree T of G. An identifying path cover of T is also one for G! In the worst case, T has many leaves (up to n - 1).

In general, for connected graphs G, we have the tight bounds:

$$\lceil \log_2(n+1)
ceil \leq p^{\scriptscriptstyle {
m ID}}(G) \leq \lceil rac{2n}{3}
ceil$$

In general, for connected graphs G, we have the tight bounds:

$$\lceil \log_2(n+1)
ceil \leq p^{\scriptscriptstyle {
m ID}}(G) \leq \lceil rac{2n}{3}
ceil$$

This an improvement over IDP, where for a connected instance:

$$\lceil \log_2(n+1) \rceil \leq p^{\scriptscriptstyle {\rm ID}}(G) \leq n$$

(see e.g. Foucaud, Naserasr, Parreau 2012 for the special case of identifying codes in digraphs).

Definition - ID. PATH COVER

INPUT: a graph GPROBLEM: find the minimum-size identifying path cover of G.

Definition - ID. PATH COVER

INPUT: a graph GPROBLEM: find the minimum-size identifying path cover of G.

Definition - ID. PATH COVER-k

INPUT: a graph GPROBLEM: find the minimum-size identifying path cover of G such that each path has at most k vertices.

Definition - ID. PATH COVER

INPUT: a graph GPROBLEM: find the minimum-size identifying path cover of G.

Definition - ID. PATH COVER-k

INPUT: a graph GPROBLEM: find the minimum-size identifying path cover of G such that each path has at most k vertices.

We know that ID. PATH COVER is $O(\log(n))$ -approximable and that ID. PATH COVER-k is $O(\log(k))$ -approximable.

Definition - ID. PATH COVER

INPUT: a graph GPROBLEM: find the minimum-size identifying path cover of G.

Definition - ID. PATH COVER-k

INPUT: a graph GPROBLEM: find the minimum-size identifying path cover of G such that each path has at most k vertices.

We know that ID. PATH COVER is $O(\log(n))$ -approximable and that ID. PATH COVER-k is $O(\log(k))$ -approximable.

Theorem (F., Kovše)

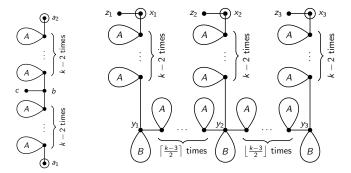
ID. PATH COVER-k is APX-hard, i.e., there exists some constant c > 1 such that it is NP-hard to approximate ID. PATH COVER-k within ratio c.

Florent Foucaud

Theorem (F., Kovše)

ID. PATH COVER-k is APX-hard, i.e., there exists some constant c > 1 such that it is NP-hard to approximate ID. PATH COVER-k within ratio c.

Proof: L-reduction from VERTEX COVER in cubic graphs. *A* and *B* are local sub-gadgets.



Open problems

- Give good **upper** bounds for TCP-*k*, IDP-*k*, ID. PATH COVER-*k* (this already seems to be a difficult question for identifying codes).
- Is there a polynomial-time algorithm for ID. PATH COVER in trees?
- What is the complexity of the general ID. PATH COVER problem?
- What are the graphs that admit a *k*-path identifying cover (i.e. all paths have **exactly** *k* vertices)?

Open problems

- Give good **upper** bounds for TCP-*k*, IDP-*k*, ID. PATH COVER-*k* (this already seems to be a difficult question for identifying codes).
- Is there a polynomial-time algorithm for ID. PATH COVER in trees?
- What is the complexity of the general ID. PATH COVER problem?
- What are the graphs that admit a *k*-path identifying cover (i.e. all paths have **exactly** *k* vertices)?

Thank you / Nandri / Shukriya / Merci!